

Reservoir characterization with ensemble Kalman filter

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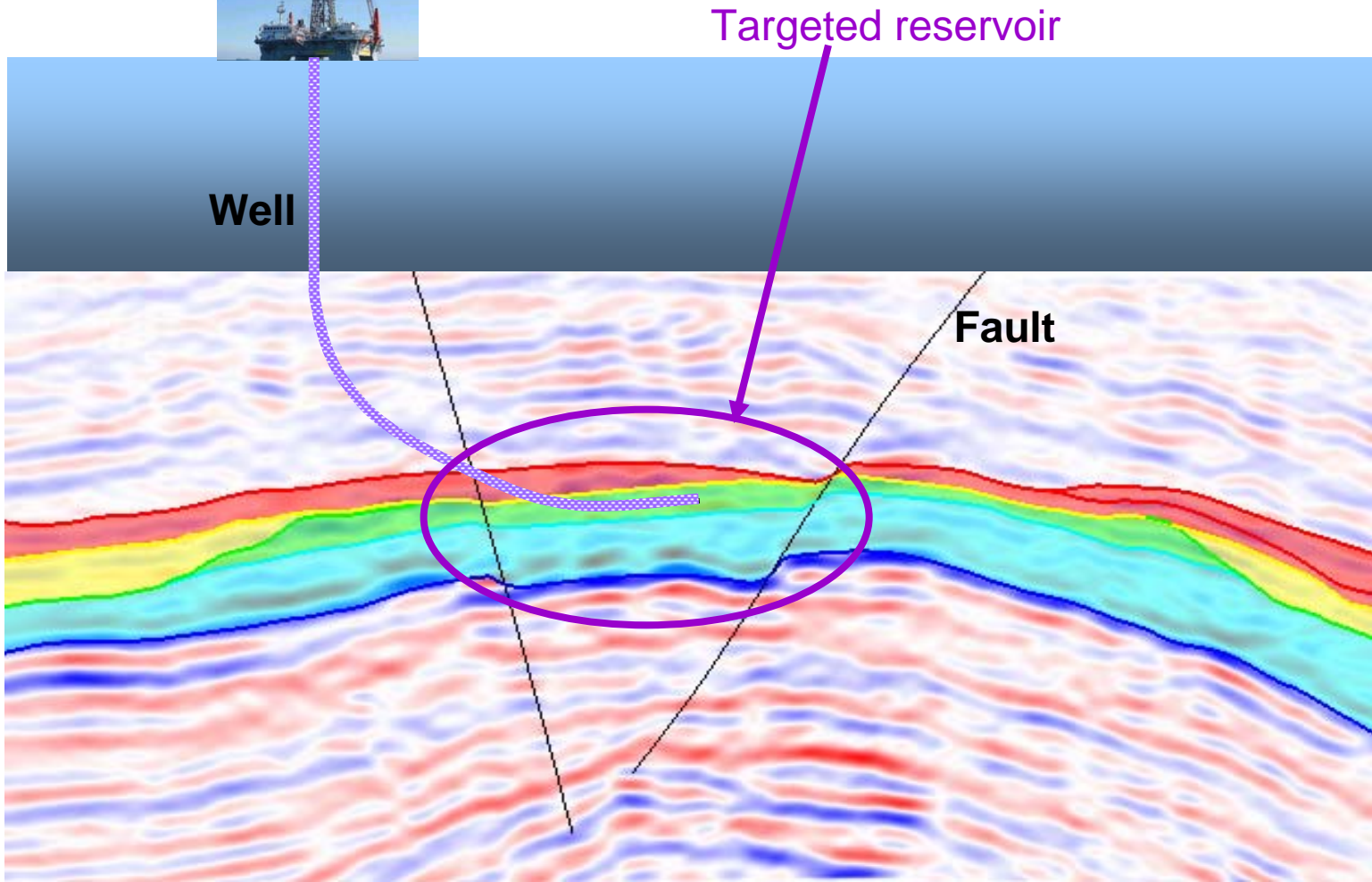
Work based on research financed by the Norwegian Research Council

Outline

- Introduction and motivation
- Ensemble Kalman filter (EnKF)
- Examples
 - North Sea field case
 - Brugge study
- Conclusion



Geological oil/gas reservoirs



Technology gap in reservoir models

- Common practice
 - Seldom update of reservoir models
 - Too time consuming
 - Insufficient uncertainty quantification
- Future vision
 - Improve workflow for updating reservoir simulation models
 - Work in real time
 - Include uncertainty quantification

Reservoir simulation models

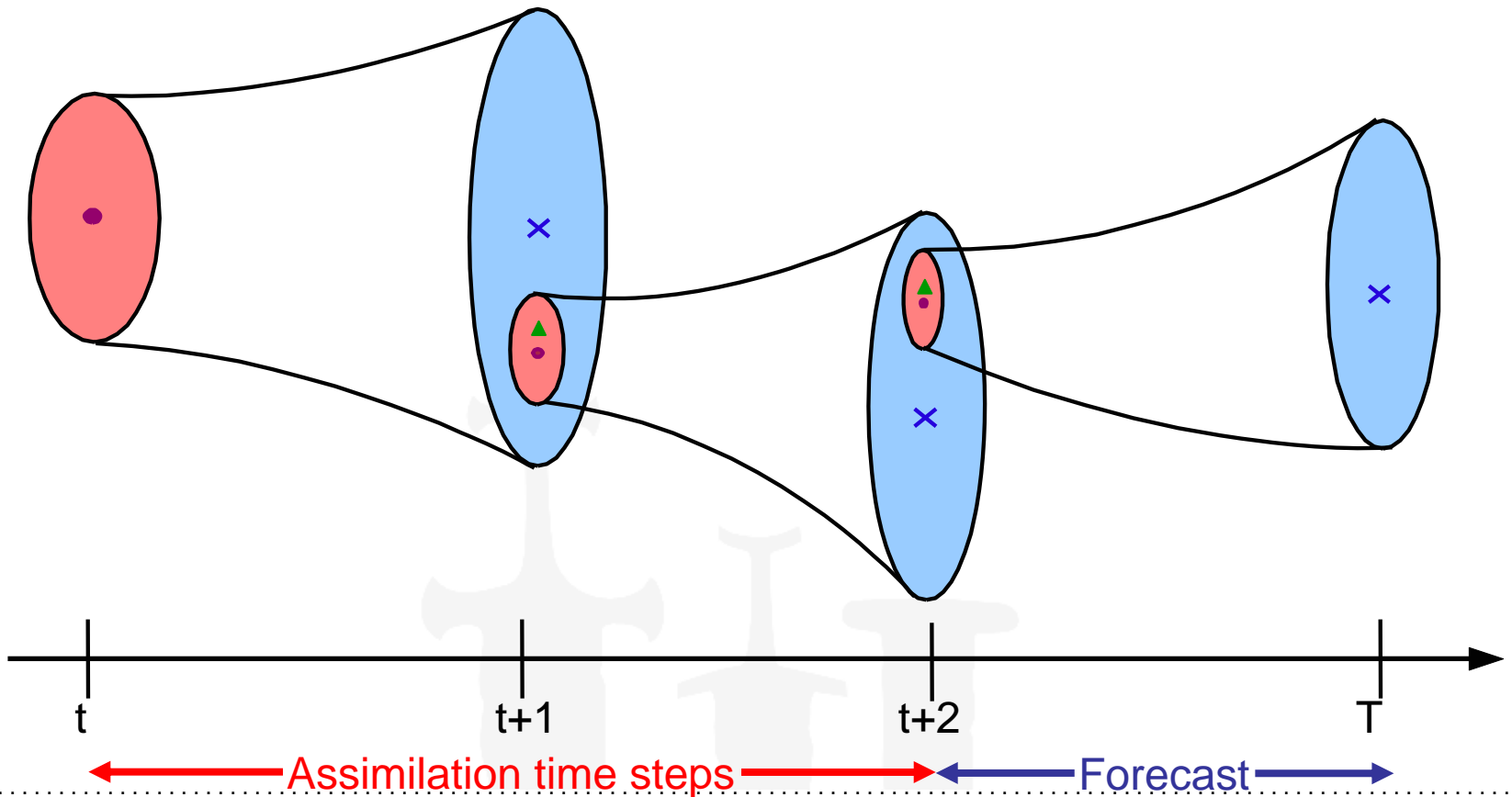
- Necessary coarse representation of geological model
 - To allow simulations in a reasonable time
- Characterized by petrophysical properties
 - Porosity
 - Permeability
- How to best characterize reservoir models?
 - Solving inverse problem using observed data
 - Bottom-hole pressure, oil production rate, water injection rate...
 - Two approaches
 - Global: invert porosity, permeability using all data in one single process
 - Sequential: update porosity, permeability each time new data are observed

Ensemble Kalman filter (EnKF)

- Introduced by Geir Evensen in 1994
 - Motivated by oceanography and atmospheric sciences
- Introduced to reservoir engineering by Nævdal (IRIS) in 2002
- Built for large scale nonlinear systems
- Bayesian framework
- Monte Carlo simulation
 - \Rightarrow ensemble of realizations
 - \Rightarrow uncertainty estimation

EnKF - schematic

- ▲ observed data
- Analyzed uncertainty
- Analyzed mean
- Forecast uncertainty
- × Forecast mean

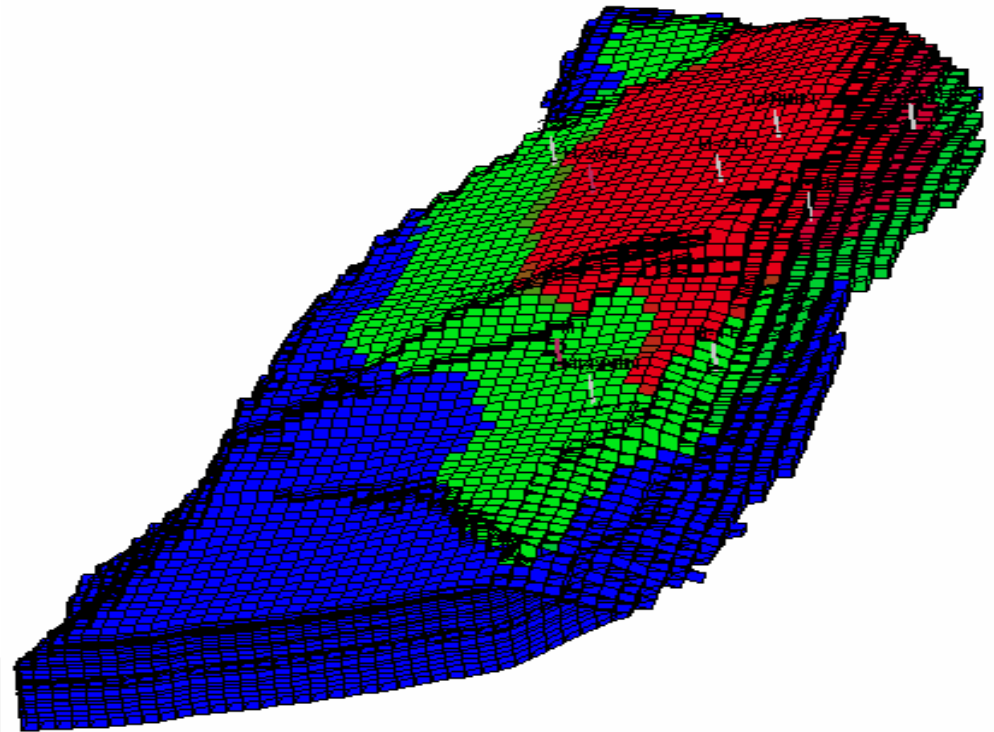


EnKF for reservoir applications

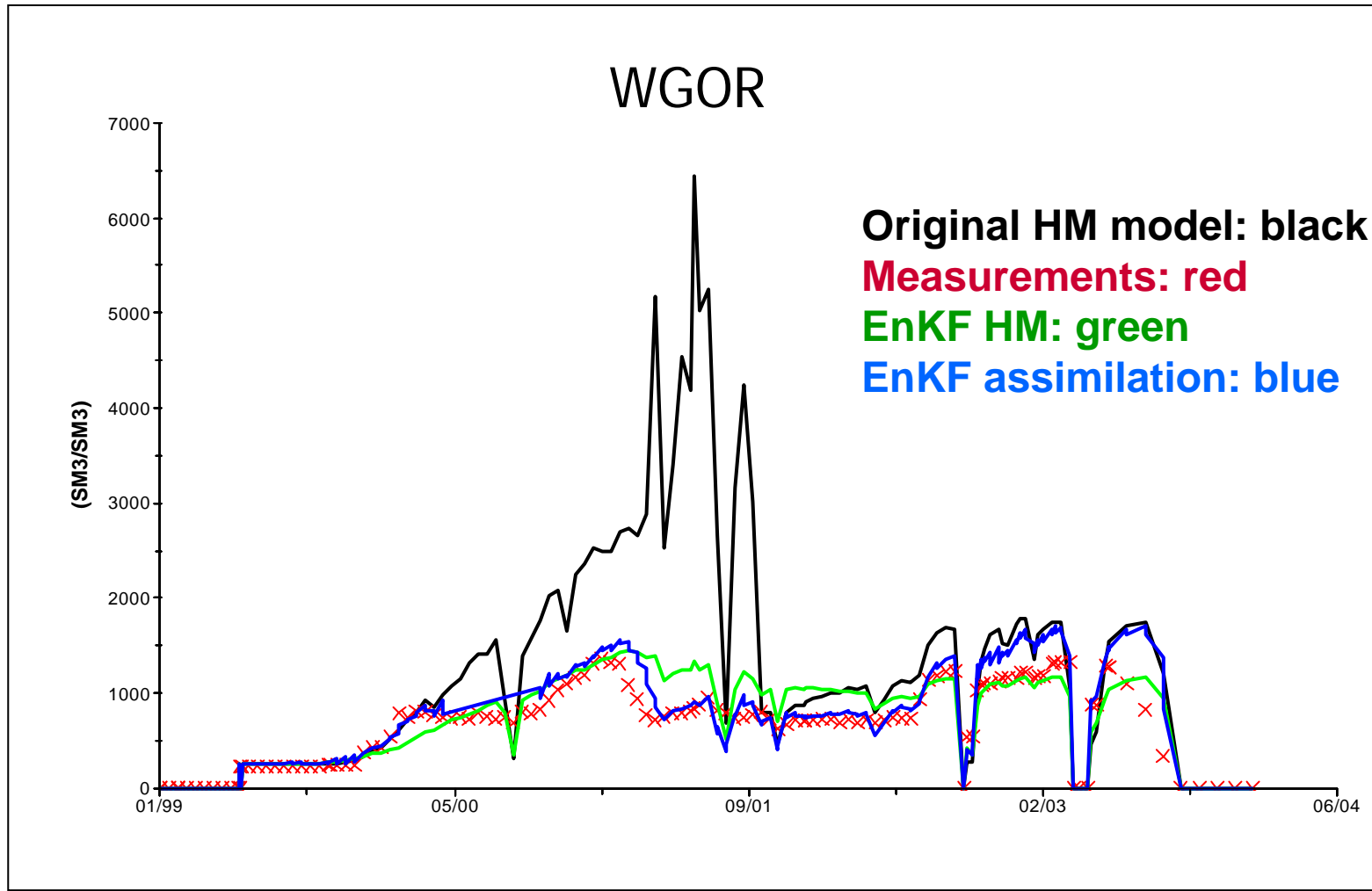
- Monte Carlo simulation
- Typically 100 ensemble members
 - 100 reservoir models!
- Computational load
 - 1 (reservoir simulator) simulation per ensemble member
 - Easy to run in parallel (1 simulation = 1 PE)
- Update
 - Porosity, permeability, pressure, saturations...
- Note: we do not say that “model parameters change in time” but “**our knowledge of model parameters improve with time**”!... hence the update

Examples

- Real Field - Haugen et al., 2006 (SPE 102430)
 - North Sea case
 - Grid size: 45 x 75 x 26
 - Active cells: 47795
 - 4 oil producers
 - 2 gas injectors

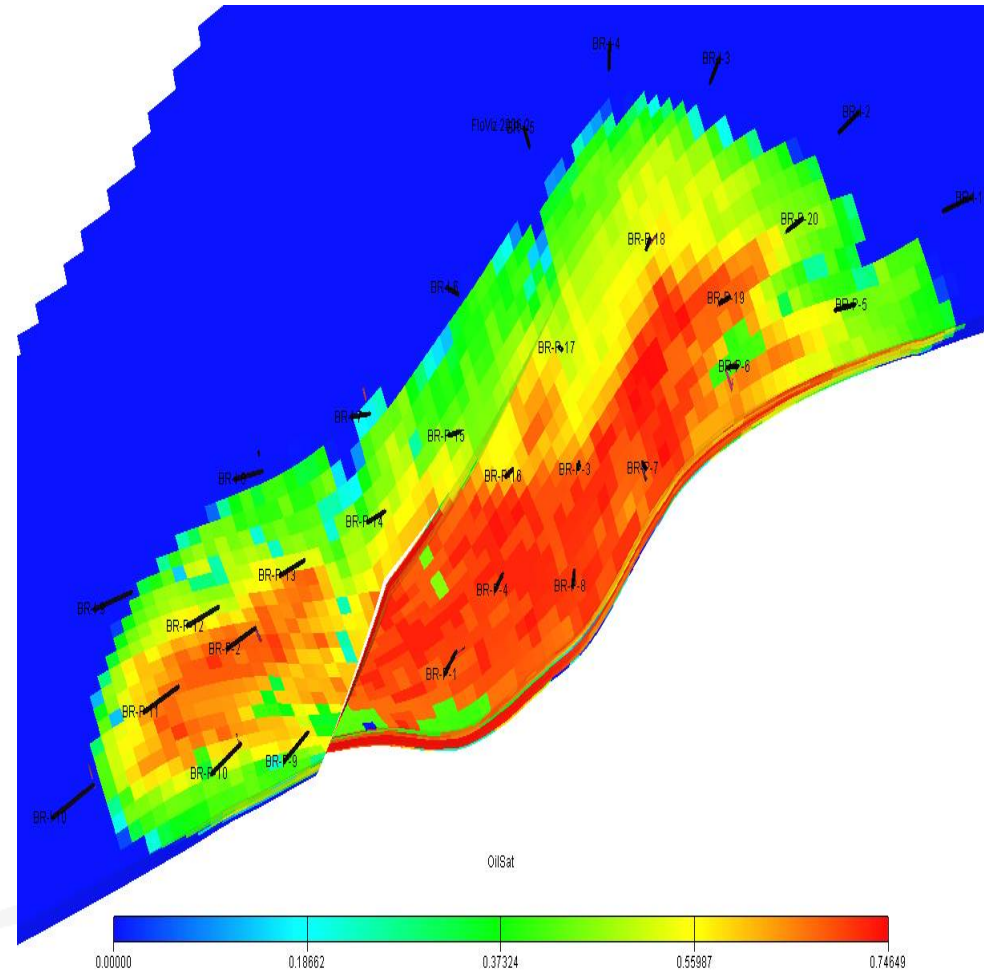


North Sea field case



Brugge field

- Brent type of reservoir
- 9 layers
- Two phases:
 - Oil & water
- 10 injectors
- 20 producers

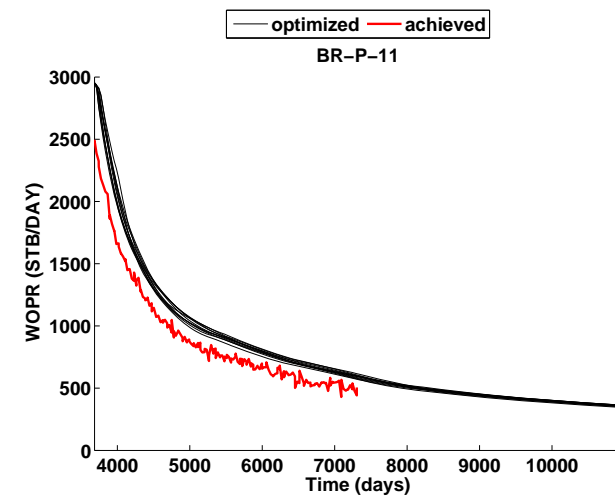
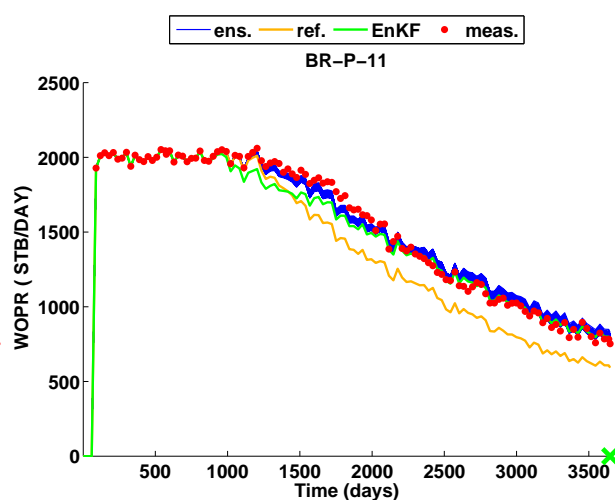
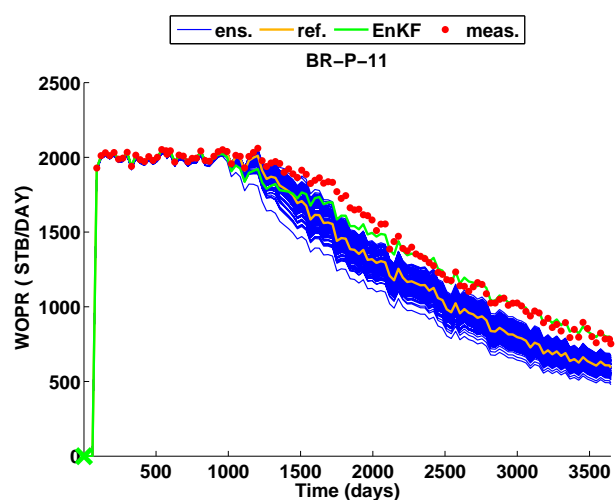
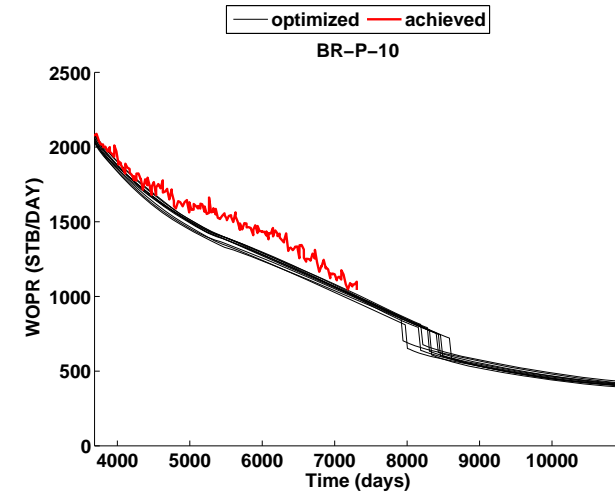
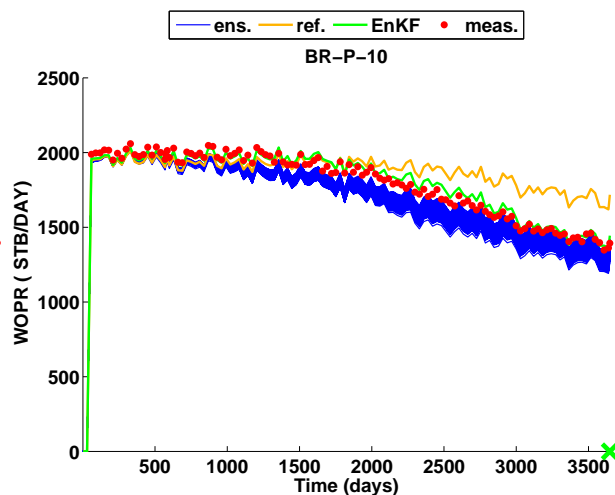
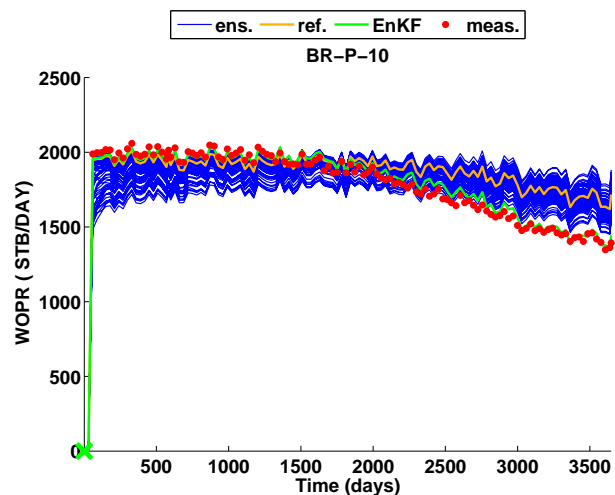


Forecasts

Before assimilation

After assimilation

After optimization



History matching phase

Optimization

NPV

	First cycle (10 ⁹ \$)	Second cycle (10 ⁹ \$)
Initial	4.39 ± 0.04	4.38 ± 0.001
Optimized	4.51 ± 0.05	4.40 ± 0.001
Achieved	4.41	4.49

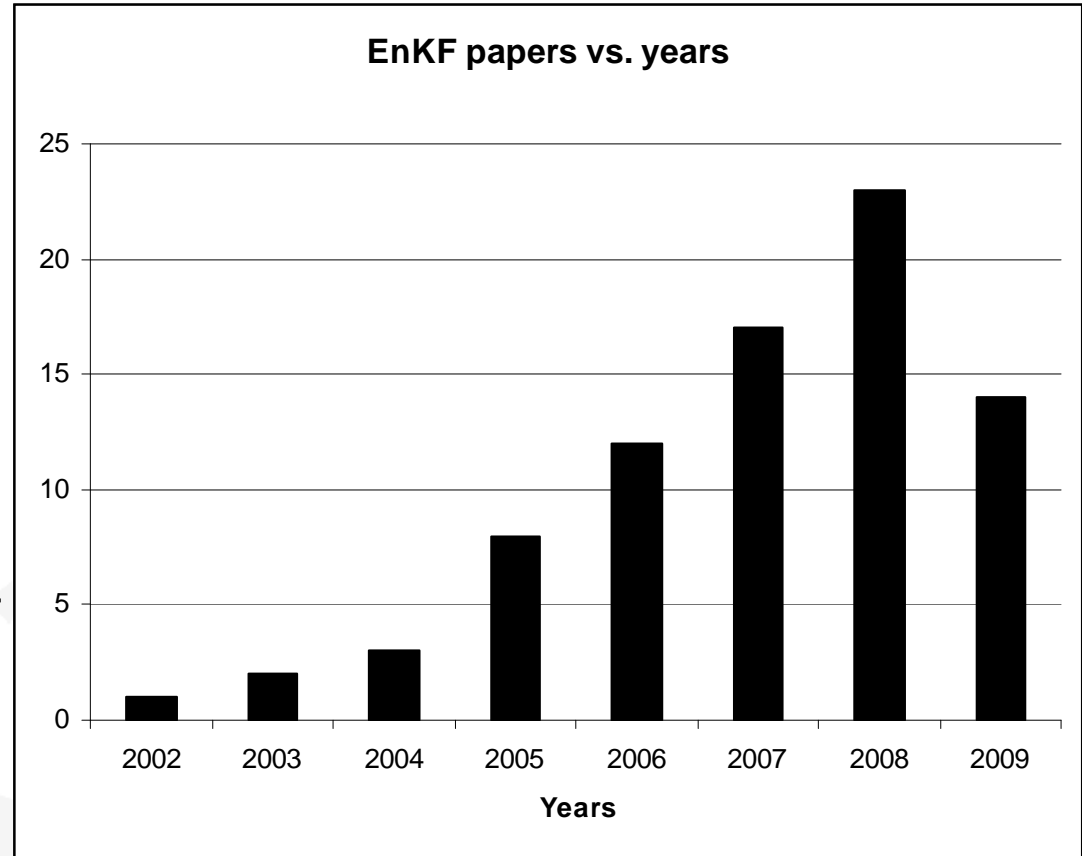
- First cycle
 - History matching: year 0 to year 10
 - Optimization: year 10 to year 30
- Second cycle (new observed data!)
 - Continue History matching: year 10 to year 20
 - Optimization: year 20 to year 30
- University of Oklahoma achieved 4.42 and 4.53

Reservoir characterization using EnKF: state of the art

- EnKF fits into a complete workflow from geostatistics to production forecasts with/without optimization
- EnKF is suitable for (semi-)automatic history matching of production data
 - Confirmed by several studies, if geostatistical model is based on variogram description
 - Can also handle other parameters than permeability and porosity (MULTFLT, MULTZ, rel-perm...)
 - Research challenge: EnKF for models based on facies
- EnKF is suitable for producing forecasts with uncertainty in real time

EnKF for reservoir applications

- Several real field studies published since 2005
- 4th international EnKF workshop
 - June 22-24, 2009
Bergen



<http://qp.rf.no/enkfseminar>